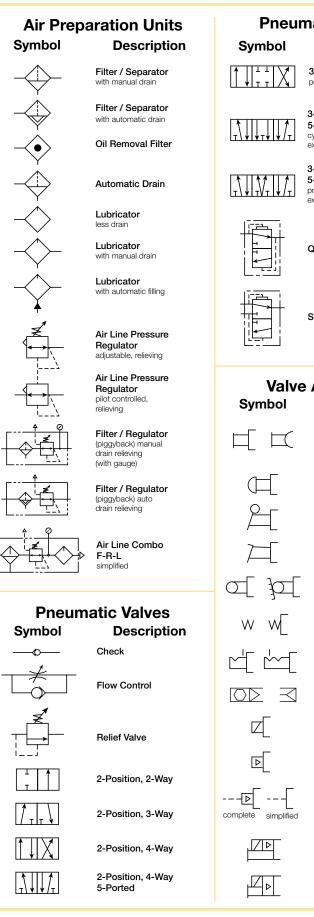
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Fluid Power Graphic Symbols								
matic Valves	Cyl	inders						
Description	Symbol	Description						
3-Position, 4-Way, APB ports closed, center pos.		Standard double acting						
3-Position, 4-Way, CE 5-Ported cylinder ports open to		Single Acting						
exhaust in center position 3-Position, 4-Way, PC 5-Ported		Double Rod						
pressure ports open to exhaust in center position		Spring Return						
		Ram Type						
Quick Exhaust		Telescope						
Shuttle		Tandum						
		Duplex						
• • •	Lines and	d Functions						
e Actuators	Symbol	Description						
Description		Solid Line – Main Line						
Manual general symbol		Dashed Line – Pilot Line Dotted Line – Exhaust						
Push Button		or Drain Line Center Line – Enclosure Outline						
	$\leftarrow \leftarrow$	Lines Crossing (90° intersection not necessary)						
Lever	+, +	Lines Joining						
Pedal or Treadle		(90° intersection not necessary)						
Mechanical	+	Lines Joining Flow Direction						
cam, toggle, etc.		hydraulic medium						
Spring	>	Flow Direction gaseous medium Energy Source						
Detent line indicates which detent is in use	->	Line with Fixed Restriction						
Piezo	1 51	Line with Adjustable						
Solenoid		Restriction						
Internal Pilot Supply		Flexible Line						
	\longrightarrow	Plugged Port, Test Station, Power Take-off						
Remote Pilot Supply	\rightarrow \leftarrow connected \rightarrow \leftarrow disconnect	Quick Disconnect ed Without Checks						
And / Or Composite solenoid and pilot or manual override		Quick Disconnect ed With Checks						
And / Or Composite solenoid and pilot or manual override and pilot	-O-+ connected -O	Quick Disconnect ed With One Check						

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Design Torque

Design torque represents the maximum torque that an actuator must supply in an application. This maximum is the greater of the Demand Torque or the Cushion Torque. If the demand torque exceeds what the actuator can supply, the actuator will either move too slowly or stall. If the cushion torque is too high, the actuator may be damaged by excessive pressure. Demand torque and cushion torque are defined below in terms of load, friction, and acceleration torque.

Equations for calculating demand torque and cushion torque for some general applications are provided on the following pages.

T - Torque

The amount of turning effort exerted by a rotary actuator.

TD - Demand Torque

This is the torque required from the actuator to do the job and is the sum of the load torque, friction torque, and acceleration torque, multiplied by an appropriate design factor. Design factors vary with the applications and the designers' knowledge.

Equation 4-3) TD = Ta + Tf + TL

TL - Load torque

This is the torque required to equal the weight or force of the load. For example, in Fig. 4-8a, the load torque is 563 Nm (5000 lb-in.); in Fig. 4-8b the load torque is zero; in Fig. 4-8c the load torque is 563 Nm (5000 lb-in.). The load torque term is intended to encompass all torque components that aren't included in the friction or acceleration terms.

Tf - Friction torque

This is the torque required to overcome friction between any moving parts, especially bearing surfaces. In Fig. 4-8a, the friction torque is zero for the hanging load; in Fig. 4-8b the friction torque is 775 Nm (6880 lb-in) for the sliding load; in Fig. 4-8c the friction torque is zero for the clamp.

Equation 4-4) Tf = mWr

Ta - Acceleration Torque

This is the torque required to overcome the inertia of the load in order to provide a required acceleration or deceleration. In Fig. 4-8a the load is suspended motionless so there is no acceleration. In Fig. 4-8b, the load is accelerated from 0 to some specified angular velocity. If the mass moment of inertia about the axis of rotation is I and the angular acceleration is a, the acceleration torque is equal to Ia. In Fig. 4-8c there is no acceleration.

Some values for mass moment of inertia are given in Table 4. Some useful equations for determining a are listed in Table 5. Equation 5 below shows the general equation for acceleration torque.

Equation 4-5) **Ta = Ia**

TC - Cushion Torque

This is the torque that the actuator must apply to provide a required deceleration. This torque is generated by restricting the flow out of the actuator (meter-out) so as to create a back pressure which decelerates the load. This back pressure (deceleration) often must overcome both the inertia of the load and the driving pressure (system pressure) from the pump. See applications.

Equation 4-6)
$$Tc = Ta + \frac{PrV}{\theta} - Tf \pm TL$$

The friction torque Tf reduces the torque the actuator must apply to stop the load. The load torque TL may add to, or subtract from the torque required from the actuator, depending upon the orientation of the load torque. For example, a weight being swung upward would result in a load torque that is subtracted.

Warning: Rapid deceleration can cause high pressure intensification at the outlet of the actuator. Always insure that cushion pressure does not exceed the manufacturer's pressure rating for the actuator.

KE – Kinetic Energy (1/2 Jmω²)

This is the amount of energy that a rotating load has. The rotator must be able to stop the load. All products have kinetic energy rating tables. Choose the appropriate deceleration option (i.e., bumper, cushions, shock absorbers, etc.) that meets or exceeds the kinetic energy of the load.



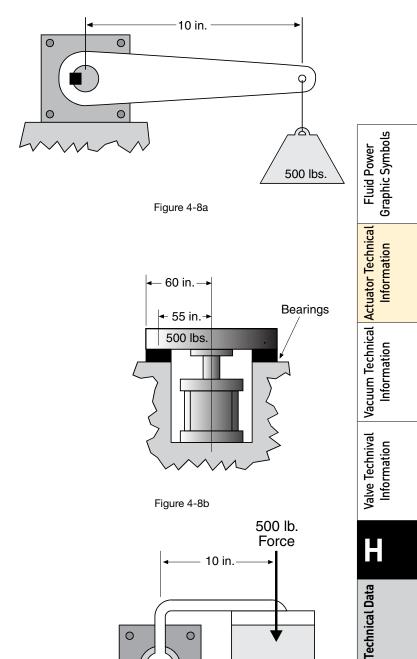
Fluid Power Actuator Techni Graphic Symbols Information

Rotary Actuator Torque Requirements Demand Torque Examples

A) Example of load torque

The load is held motionless as shown.

 $TD = T\alpha + Tf + TL$ $T\alpha = 0$ Tf = 0TL = (500 lb)(10 in) = 5,000 lb-in TD = 5,000 lb-in



B) Due to friction and acceleration

The 500 lb rotating index table is supported by bearings with a coefficient of friction of 0.25. The table's acceleration a is 2 rad/ sec². The table's mass moment of inertia I is 2,330 lb-in-sec².

 $TD = T\alpha + Tf + TL$

 $T\alpha = I\alpha = (2,330 \text{ lb-in-sec2})(2/\text{sec2}) = 4,660 \text{ lb-in}$

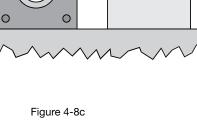
 $Tf = \mu Wrb = 0.25 (500 \text{ lb})(55 \text{ in}) = 6,880 \text{ lb-in}$

TL = 0

TD = 4,660 lb-in + 6,880 lb-in = 11,540 lb-in

C) Load torque example

 $\mathsf{T}\mathsf{D} = \mathsf{T}\alpha + \mathsf{T}\mathsf{f} + \mathsf{T}\mathsf{L}$ $T\alpha = 0$ $T_f = 0$ $T_{L} = (500 \text{ lb})(10 \text{ in}) = 5,000 \text{ lb-in}$ TD = 5,000 lb-in



0

0



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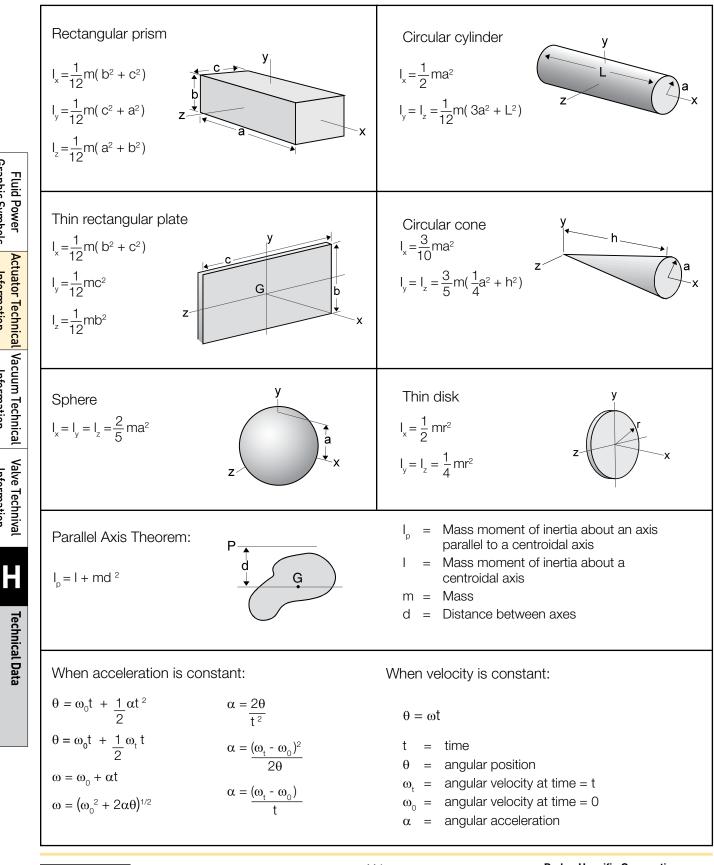
Rotary Actuator Moments of Inertia Table 4: Mass Moments of Inertia

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Rotary Actuator Basic Equations Basic Velocity, Acceleration, Kinetic Energy And Torque Equations

Equations below a	are based on triangular velocity profile.	
$\omega_{\text{max}} = .035 \times \frac{\Theta}{t}$ $\alpha = \frac{\omega_{\text{max}^2}}{\left(\frac{\Theta}{57.3}\right)}$	Where: Θ = Angle of Rotation (Degrees) t = Time to rotate through Θ (sec) ω = Angular velocity, radians/sec α = Angular accelerations (radians/sec ²) WL = Weight of load (lbf)	Fluid Power
$\alpha = \frac{\omega_{\text{max}}}{(t/2)}$	 Ta = Torque to accelerate load (lb-in) Us = Coefficient of static friction Jm* = Rotational mass moment of inertia (lb-in-sec2) 	
K.E. = $1/2 \operatorname{Jm} \omega^2$ Ta = $\alpha \times \operatorname{Jm}$	 Tf = Torque to overcome friction (lb-in) TL = Torque to overcome effects of gravity *Use "I" values from Table 4. 	Actuator Techni
$T_f = W \times U_s \times \begin{pmatrix} \text{Distance from pivot} \\ \text{center of external be} \end{pmatrix}$	point to earings	Vacuum Technical Actuator Technical
$T_{L} = \left(\begin{array}{c} \text{Torque arm length} \\ \text{to C.G. of load} \end{array} \right) \times WL \times \cos \theta$ $Where \phi = \text{Angle between torque arm} \\ \text{and horizontal plane}$	> (ψ)	Valve Technival

Coefficients of Friction

Material*	μs	μĸ
Steel on Steel	0.80	0.40
Steel on Steel (lubricated)	0.16	0.03
Aluminum on Steel	0.45	0.30
Copper on Steel	0.22	0.22
Brass on Steel	0.35	0.19
Teflon on Steel	0.04	0.04

*dry contact unless noted



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Selecting the proper vacuum cup

CAUTION:

Selecting the type of vacuum cup, material, and size suitable for an application is important to the overall vacuum system. Calculating the forces involved for each application is recommended to determine the vacuum cup size. It should be noted that these calculations are basic theoretical guidelines and each application must be tested for actual results. With all vacuum applications, certain practical assumptions concerning cup materials, environmental conditions, and product characteristics to name a few, may not be consistent with the performance. Again, the user should determine the efficiency, performance, and safety factor of the cup selection.

Calculating pad diameter and forces

Mass

The term mass is a quantity of matter and its ability to resist motion when acted on by an external force. The magnitude of an object is represented as a certain number of kilograms (kg) and is symbolized as "m". The easiest way to determine the mass of an object is to measure the weight with a scale within the earth's gravitational field (ag = 9.81m/sec²). Likewise, outside of any gravitational field, a mass could potentially be weightless.

Forces

For vacuum applications, force is a vector quantity in a defined direction either horizontal or vertical. The standard international unit of force is measured in Newtons (N) which is the equivalent of (kgm/sec²). The force can be calculated by measuring the effect of a change in acceleration on a mass.

Newtons Law: $F(N) = mass(kg) \times a_g(m/sec^2)$

Consider an object with a mass of 10kg. The gravitational force on this object would be:

 $F(N) = 10 kg \times 9.81 m/sec^2 = 98.1 N$

Acceleration

Acceleration is the change in velocity of a moving object. Acceleration is a vector, a directional quantity expressed in units of meters per second squared (m/ sec²) and symbolized as "a". To explain the magnitude of acceleration consider an object with a change in velocity of 2 meters per second (m/sec) over a 4 second time frame. The acceleration can be calculated with: $a = \triangle$ velocity a = 6m/sec $a = 3m/sec^2$ time 2 sec

This is considered an average acceleration.

Coefficient of friction

Certain values for coefficient of friction should be taken into consideration when calculating the combined forces in motion. Actual values between suction cups and surfaces are difficult to determine. Therefore, coefficient of friction values from published charts, should be used as a reference to adjust the safety factors accordingly.

Lifting forces

When calculating lifting forces, safety factors of 2 for horizontal lifts and 4 for vertical lifts are minimum values. Applications with irregular shapes, difficult surfaces, and backward motions will require increased safety factors.





Fн: Horizontal Lift

Fv: Vertical Lift

Horizontal lifting force

Apply Newtons Law to calculate the force on a 10kg mass with a change in acceleration of 3m/sec² and a safety factor of 2.

 $FH(N) = mass(kg) \times (a_{\alpha} + a) \times SH$

FH(N) = 10kg x (9.81m/sec² +3m/sec²) x 2

FH = 256.2 N



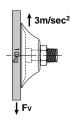
Vertical lifting force

Apply Newtons Law to calculate the force on a 10kg mass with a dry surface, a change in acceleration of 3m/sec² and a safety factor of 4.

 $FV(N) = mass(kg) \times (a_g + a) \times Sv$

 $FV(N) = 10kg \times (9.81m/sec^2 + 3m/sec^2) \times 4$

FV = 512.4 N



Combined vertical lift and horizontal motion

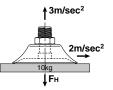
Calculate the force on a 10kg mass with a dry surface, a change in acceleration of 3m/sec², and a change in travel acceleration of 2m/sec².

 $FM(N) = \sqrt{FV^2 + FH^2}$

$$FM(N) = \sqrt{[(10 \text{kg x } 2\text{m/sec}^2) \text{ x } 4]^2 + [10 \text{kg x } (9.81 \text{m/sec}^2 + 3 \text{m/sec}^2) \text{ x } 2]^2}$$

 $FM(N) = \sqrt{(80 \text{kgm/sec}^2)^2 + [256 \text{kgm/sec}^2]^2}$

 $FM(N) = \sqrt{6400 \text{kgm/sec}^2 + 65,536 \text{kgm/sec}^2}$



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Analyze the forces

Using the previous examples, consider an application where 4 cups have been selected to transfer the product.

Take the Horizontal Lifting Force (FH) of 256.2 N and divide by the number of cups (4) to obtain the individual force for each cup.

Referring to the chart below, at 60% vacuum, select a force greater than 64.05 N. The appropriate selection is a 40mm diameter cup which has a theoretical lifting force of 76.9 N.

The same calculation can be applied to the Vertical Lifting Force and the Forces in Motion examples to determine the cup diameter.

To convert Pounds (lbf) to Newton (N), multiply lbf x 4.4.

Theoretical lifting force per cup lbf (N)

Calculate the diameter of the cup

Calculate the cup diameter for horizontal lift at 60% of full vacuum using the information from the previous page.

$$D = 35.7 \sqrt{\frac{m (a_g + a) \times S}{Pv \times n}}$$

$$D = 35.7 \sqrt{\frac{10 (9.81 + 3) \times 2}{61 \times 4}}$$

$$D = 0 \text{ (mm)} = \text{Diameter of Cup}$$

$$D = 0 \text{ (mm)} = \text{Diameter of Cup}$$

$$D = 0 \text{ (mm)} = \text{Diameter of Cup}$$

$$m (kg) = \text{Mass}$$

$$a_g = 9.81 \text{ (msc)}$$

$$a = \text{Motion Acceleration}$$

$$S = \text{Safety Factor}$$

$$Pv (kPa) = \text{Operating Vacuum}$$

eleration ating Vacuum Pressure n = number of Cups

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D = 36.58 mm

Referring to the chart below, at 60% vacuum, select a cup diameter equal to or greater than 37mm. The appropriate selection is a 40mm diameter cup which has a theoretical lifting force of 76.9 N.

Cup						Vacuum leve				
oup		3 inHg	6 inHg	9 inHg	12 inHg	15 inHg	18 inHg	21 inHg	24 inHg	27 inHg
Diameter	Area	-1.5 PSIG	-3 PSIG	-4.5 PSIG	-6 PSIG	-7.5 PSIG	-9 PSIG	-10.5 PSIG	-12 PSIG	-13.5 PSIG
mm	cm ²	10.2 kPa 10%	20.3 kPa 20%	30.5 kPa 30%	40.6 kPa 40%	50.8 kPa 50%	61 kPa 60%	71.1 kPa 70%	81.3 kPa 80%	91.4 kPa 90%
		0.004	0.008	0.008	0.014	0.018	0.022	0.026	0.032	0.032
1.5	0.01	(0.02)	(0.008	(0.04)	(0.06)	(0.08)	(0.10)	(0.12)	(0.14)	(0.14)
		0.007	0.013	0.022	0.029	0.036	0.043	0.049	0.056	0.063
2	0.03	(0.03)	(0.06)	(0.10)	(0.13)	(0.16)	(0.19)	(0.22)	(0.25)	(0.28)
3.5	0.10	0.022	0.045	0.065	0.088	0.110	0.133	0.155	0.175	0.198
0.0	0.10	(0.10)	(0.20)	(0.29)	(0.39)	(0.49)	(0.59)	(0.69)	(0.78)	(0.88)
5	0.20	0.045	0.090	0.135	0.180	0.225	0.270	0.315	0.360	0.405
-		(0.20)	(0.40)	(0.60)	(0.80)	(1.00)	(1.20)	(1.40)	(1.60)	(1.80)
6	0.28	0.065 (0.29)	0.130 (0.58)	0.196 (0.87)	0.270 (1.20)	0.315 (1.40)	0.382 (1.70)	0.450 (2.00)	0.517 (2.30)	0.585 (2.60)
		0.088	0.175	0.265	0.360	0.450	0.540	0.607	0.697	0.787
7	0.39	(0.39)	(0.78)	(1.18)	(1.60)	(2.00)	(2.40)	(2.70)	(3.10)	(3.50)
0	0.50	0.117	0.229	0.346	0.450	0.585	0.697	0.809	0.922	1.034
8	0.50	(0.52)	(1.02)	(1.54)	(2.00)	(2.60)	(3.10)	(3.60)	(4.10)	(4.60)
10	0.79	0.180	0.360	0.540	0.719	0.899	1.079	1.259	1.439	1.619
	0.10	(0.80)	(1.60)	(2.40)	(3.20)	(4.00)	(4.80)	(5.60)	(6.40)	(7.20)
15	1.77	0.404	0.809	1.216	1.619	2.023	2.428	2.833	2.237	3.642
		(1.80)	(3.60)	(5.41)	(7.20)	(9.00)	(10.8)	(12.6)	(14.4) 4.676	(16.2) 5.238
18	2.55	(2.60)	(5.20)	(7.79)	(10.4)	(13.0)	(15.6)	4.069 (18.1)	4.676 (20.8)	(23.3)
		0.719	1.439	2.158	2.878	3.597	4.316	5.036	5.755	6.474
20	3.14	(3.20)	(6.40)	(9.60)	(12.8)	(16.0)	(19.2)	(22.4)	(25.6)	(28.8)
25	4.91	1.124	2.248	3.372	4.496	5.620	6.744	7.868	8.992	10.116
20	4.91	(5.00)	(10.0)	(15.0)	(20.0)	(25.0)	(30.0)	(35.0)	(40.0)	(45.0)
30	7.07	1.619	3.237	4.856	6.474	8.093	9.712	11.330	12.949	14.568
		(7.20)	(14.4)	(21.6)	(28.8)	(36.0)	(43.2)	(50.4)	(57.6)	(64.8)
35	9.62	2.203 (9.80)	4.406 (19.6)	5.598 (29.4)	8.813 (39.2)	11.016 (49.0)	13.241 (58.9)	15.422 (68.6)	17.648 (78.5)	19.828 (88.2)
		2.900	5.755	8.655	11.510	14.388	17.288	20.143	23.155	25.853
40	12.6	(12.9)	(25.6)	(38.5)	(51.2)	(64.0)	(76.9)	(89.6)	(103)	(115)
50	10.0	4.519	8.992	13.511	17.985	22.481	26.977	31.473	35.969	40.466
50	19.6	(20.1)	(40.0)	(60.1)	(80.0)	(100)	(120)	(140)	(160)	(180)
60	28.3	6.497	12.949	19.446	25.853	32.372	38.892	45.411	51.931	58.226
	20.0	(28.9)	(57.6)	(86.5)	(115)	(144)	(173)	(202)	(231)	(259)
75	44.2	10.161 (45.2)	20.233 (90.0)	30.349 (135)	40.466 (180)	50.582 (225)	60.698 (270)	70.815 (315)	80.931 (360)	91.048 (405)
		11.555	22.931	34.621	46.086	57.551	69.241	80.706	92.172	103.637
80	50.3	(51.4)	(102)	(154)	(205)	(256)	(308)	(359)	(410)	(461)
		14.635	29.225	43.838	58.226	72.838	87.451	102.063	116.676	131.064
90	63.6	(65.1)	(130)	(195)	(259)	(324)	(389)	(454)	(519)	(583)
95	70.9	16.299	32.372	48.784	64.970	81.156	97.567	113.753	129.940	146.126
90	70.9	(72.5)	(144)	(217)	(289)	(361)	(434)	(506)	(578)	(650)
110	95.0	21.851	43.613	65.419	87.001	108.808	130.614	152.421	174.227	195.809
		(97.2)	(194)	(291)	(387)	(484)	(581)	(678)	(775)	(871)
120	113.1	26.078 (116)	51.706 (230)	77.784 (346)	103.637 (461)	129.490 (576)	155.568 (692)	181.421 (807)	207.274 (922)	233.127 (1037)
		40.690	80.931	121.622	161.862	202.328	243.019	283.259	323.950	364.191
150	176.7	(181)	(360)	(541)	(720)	(900)	(1081)	(1260)	(1441)	(1620)
200	314.2	72.164	143.878	216.041	287.531	359.919	432.083	503.797	575.961	647.449
200	314.2	(321)	(640)	(961)	(1279)	(1601)	(1922)	(2241)	(2562)	(2880



Parker Hannifin Corporation Pneumatic Division

Richland, Michigan www.parker.com/pneumatics

Selecting a generator size

The choice of Generator Series depends on the system requirements for components and overall performance for the application. Inline Generators offer the basic function for creating vacuum flow. Adding integrated components such as automatic blow off Controls, Vacuum and Blow-off Solenoids, Pressure Sensors, Check Valves and Filters are options that can reduce overall mounting space, reduce cycle time and can offer air conservation functions as well as emergency stop modes. For guidelines on selecting Vacuum Generators by features, consult the highlight features in the Generator Index section for each Series Section.

A vacuum source can only achieve and hold a degree of vacuum that sustains the amount of leakage into the vacuum system. In most cases, it is the leakage through the product and by of the cup seal that limits the system degree of vacuum. Products with high product leakage are Porous Applications. The degree of vacuum that can be obtained with this type of product can vary and tends to be below 10 inHg. Products with low or no leakage are called Non-Porous Applications. It can be assumed that the maximum degree of vacuum of the system is the maximum degree of the vacuum generator. Due to design cycle time and safety requirements, a lower degree of vacuum is generally chosen other than the maximum obtainable degree of vacuum. Chart 1 lists different units of measure for vacuum with typical application levels The system degree of vacuum must be determined by product testing.

Evacuation time

The size of the generator generally refers to either the Evacuation Time or the Vacuum Flow Rates of the generator and varies by the size of the nozzle / diffuser.

Evacuation Time is the time required to evacuate the air out of a vacuum system to specific degree of vacuum. Typically, this degree of vacuum is a value where it is safe to move a product in a pick and place application and is determined by the design engineer. Evacuation Time can also be considered response time of the system.

A typical Evacuation Time chart for a generator series is shown in Chart 2. The time to achieve a given degree of vacuum in a 1 cubic foot volume is listed in seconds for each Generator.

Chart 1: Basic vacuum pressure measurements units

Negative gauge pressure PSIG	Absolute pressure PSIA	Inches of mercury inHg				
0	14.7	0				
Atmospheric press	ure at sea level					
-1.5	13.2	3				
-3.0	11.7	6				
-4.5	10.2	9				
Typical porous vacu	uum level					
-6.0	8.7	12				
-7.5	7.2	15				
-9.0	5.7	18				
-10.5	4.2	21				
Typical non-porous	vacuum level					
-12.0	2.7	24				
-13.5	1.2	27				
-14.7	0	29.92				
Perfect vacuum (zero reference pressure)						

Example: A pick and place application requires a 0.25 secs for creation of 18 inHg of vacuum in the vacuum system. The vacuum system volume, which includes tubing and cups, is 0.002 ft^3 .

The evacuation time charts are given for a 1 cubic foot (ft³) volume. To use these charts, convert the time requirement of the system to an equivalent time for a 1 cubic foot (ft³) volume. In this example, 1 cubic foot (ft³) is 500 times the system volume of 0.002 ft³. Multiply the system time requirement by 500 (500 x 0.25 secs = 125 seconds). Any generator with a evacuation time of less than 125 seconds to attain 18 inHg can be chosen for this application. A CV-15-HS will meet the requirements for this application. A (-) listed means the generator will not obtain a higher degree of vacuum than the level of the first (-).

Chart 2: evacuation time

Series / nozzle diameter	Air supply pressure	Air consumption	Evacuation time in sec / ft3 * to reach different vacuum levels (inHg)								
	PSI	SCFM	3	6	9	12	15	18	21	24	27
CV-05HS	70	0.46	24.3	57.3	101.0	160.5	231.1	305.1	433.1	597.7	_
CV-05LS	70	0.46	11.0	23.4	40.0	64.4	110.2	_	_	_	_
CV-10HS	70	1.55	4.8	9.9	16.0	24.9	35.9	51.4	77.4	117.5	226.0
CV-10LS	70	1.55	3.7	7.6	13.0	20.3	33.1	_	_	_	_
CV-15HS	70	3.53	2.5	4.8	7.0	11.0	15.5	22.0	31.9	46.6	112.1
CV-15LS	70	3.53	2.0	3.1	5.0	7.6	12.1	_	_	_	_
CV-20HS	70	6.36	1.7	2.8	5.0	6.5	9.0	13.0	18.9	27.4	60.7
CV-20LS	70	6.36	1.3	2.5	4.0	5.9	11.3	_	_	_	_

* 1 ft3 = 28.31 liters

Tht = 20.01 mere



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Vacuum flow

A typical Vacuum Flow chart for a generator series is listed in Chart 3. The vacuum flow rate at given degree of vacuum is listed in SCFM for each Generator. This chart is generally used to determine the change of degree of vacuum given a change in vacuum flow rate of a generator.

Example. A CV-15HS can only obtain 9 inHg. The vacuum flow rate at 9 inHg is 1.50 SCFM. This means that the cup

Chart 3: Vacuum flow (SCFM)

seal and product leaks 1.50 SCFM of air. This generator can maintain the leak rate of 1.50 SCFM. Choosing a generator

with more flow at 9 inHg will increase the degree of vacuum in the system because the generator can overcome more leakage. In this case, the vacuum flow rates are linear since this CV generator is a single stage venturi generator. Replacing a CV-15HS with CV-20HS will increase the degree of vacuum in the system to approximately 16.2 inHg. The CV-20HS now maintains 16.2 inHg at a flow rate of 1.50 SCFM.

Nozzle	inHg										
diameter	0	3	6	9	12	15	18	21	24	27	30
CV-05HS	.21	.19	.17	.15	.13	.11	.09	.07	.05	.03	_
CV-05LS	.32	.27	.22	.17	.12	.06	-	_	-	-	_
CV-10HS	.95	.85	.75	.65	.55	.45	.35	.25	.15	.05	_
CV-10LS	1.27	1.05	.83	.59	.38	.17	-	_	_	_	_
CV-15HS	2.22	1.98	1.74	1.5	1.26	1.01	.76	.51	.25	.10	_
CV-15LS	3.35	2.79	2.23	1.67	1.10	.53	—	—	_	_	—
CV-20HS	3.88	3.45	3.02	2.59	2.16	1.73	1.30	.87	.44	.25	_
CV-20LS	5.85	5.09	4.03	2.97	1.91	.85	_	_	_	_	_

Tubing reference

Tubing I	ID	Tubing length (L		
SAE	mm	In.	М	
5/64	2	18	.457	
3/32	2.38	24	.610	
1/8	3.17	30	.762	
5/32	4	36	.914	
3/16	4.76	42	1.07	
1/4	6.35	48	1.22	
5/16	8	54	1.37	
3/8	9.52	60	1.52	
7/16	11.1	66	1.67	
SAE x 25	5.4 = mm	ln. x 254	= M	

Pad	volume	reference	(p _v)
-----	--------	-----------	-------------------

PFG			F
Ø	Cu in.	L	Ģ
2	.00004	.0000006	
3.5	.0001	.000002	-
5	.0003	.000005	2
5 6 8	.00048	.000008	- 3
8	.002	.00003	
10	.004	.00007	- 5
15	.012	.0002	- 7
20	.03	.0005	
25	.067	.0011	-
30	.067	.0011	
35	.14	.0023	
40	.18	.003	-
50	.25	.0042	-
60	.57	.0094	-
80	1.28	.021	-
95	1.95	.032	_
110	5.00	.082	_
150	10.80	.177	-
200	23.24	.381	-

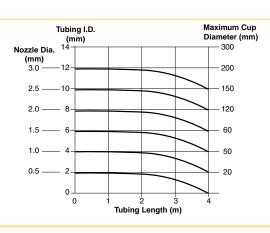
PBG			PCG
ø	Cu in.	L	ø
10	.013	.0002	5
15	.045	.0007	7
20	.070	.001	10
30	.28	.004	15
40	.56	.009	18
50	1.60	.026	20
75	4.63	.076	30
110	6.77	.111	40
150	15.86	.26	60
			90

ft3 = 28.31 liters ft³ = 1728 in³

Nozzle diameter to tubing diameter to cup diameter reference

For each application, the size of the nozzle diameter, vacuum tubing I.D., and maximum cup diameter must be practical in relationship to each other. The chart to the right is a quick reference to aid in selecting the vacuum tubing I.D. and nozzle diameter given the maximum cup diameter.

As an example, one 60mm cup with 2 meters in tubing length would require a minimum 6mm I.D. vacuum tube and a 1.5mm nozzle. The same 60mm cup with 3.5 meters in tubing length would require a minimum 8mm I.D. vacuum tube and a 2.0mm nozzle to achieve an equivalent performance.



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Cu in.

.002

.003

.010

.060

.082

123

.595

1.15

4.40

10.00

L

.00003

.00004

.0001

.0009

.001

.002

.009

.018

.072

.1639



Saving Money and Space by Sizing Your Valves Properly

This catalog gives you a flow rating (Cv) for each valve in the Parker Hannifin line. You can "plug" your requirements into the following simple formula, and determine the Cv needed to do the job. By not oversizing, you'll save space and money, and you'll ensure the valve you select will do the job.

Converting the Job Requirements Into Cv

(Capacity Co-efficient).

Cylinder Area	Cylinder	Compression		"A"
(Sq. In.) X	Stroke X	K Factor	Х	(Table 2)
Cv = (See Table 1)	(ln.)	(Table 2)		
Str	oke Time (s	ec.) x 28.8		
Let's work through an ex	xample:			
We want to extend a 3-	1/4" bore c	ylinder which h	as	a 12"
stroke in one second, ar	nd we have	a supply press	sure	e of
80 PSI to do the work. H	Here's what	we know:		
Cylinder Area for a 3-1/4	4" Bore, fro	m Table 1	8	.30 sq. in.
Cylinder Stroke				12 in.
Stroke Time Required in	Seconds			1 sec.
Compression Factor at 8	80 PSI, fror	n Table 2		6.4
"A" Constant for 80 PSI,	, from Table	2		
Substituting in the formu	ula, we have	ə:		
8.3	0 x 12 x 6.4	1 x .048		
Cv =	1 00 1	= 1.0	6	

$$\mathbf{C_V} = \frac{8.30 \times 12 \times 6.4 \times .048}{1 \times 28.8} = \mathbf{1.06}$$

Any valve, therefore, which has a Cv of at least 1.06, will extend our cylinder the specified distance in the required time.

Choosing the Valve "Series"

Your next step is to choose a basic valve design to do the job. For a guick guide to valve designs, see Table 3.

Having selected the basic valve design, consult the Capacity Co-efficient (Cv) tables which describe the individual valve capacities.

Selecting the Valve Model, Options and Accessories

Having determined Cv, series, port size, flow-path configuration (pre-determined by circuit design), and actuation method, you're ready to choose the exact valve model number.

Read the pertinent catalog pages; note the exact model numbers, options and accessories you want. Then phone or write your Parker Hannifin air valve distributor. They will give you prompt, accurate service.

Note: Need circuit design help? Contact your local Parker Hannifin distributor. They are backed up by our regional Sales Engineers and offices. Between them, you'll find answers to all of your questions.

Table 1

Effective Square-Inch Areas for Standard-Bore-Size Cylinders

Bore Size	Cylinder Area (Sq. In.)	Bore Size	Cylinder Area (Sq. In.)
3/4"	.44	4"	12.57
1"	.79	4-1/2"	15.90
1-1/8"	.99	5"	19.64
1-1/4"	1.23	6"	28.27
1-1/2"	1.77	7"	38.48
1-3/4"	2.41	8"	50.27
2"	3.14	10"	78.54
2-1/2"	4.91	12"	113.10
3-1/4"	8.30	14"	153.94
3-5/8"	10.32		

Table 2

Compression Factors and "A" Constants

Joinpico			Stants	
Inlet Pressure (PSIG)	Compression Factor	"A" Constants for Various Pressure Drop*		
		2 PSI ∆P	5 PSI ∆P	10 PSI ∆P
10	1.6	.152	.103	
20	2.3	.126	.084	.065
30	3.0	.111	.073	.055
40	3.7	.100	.065	.048
50	4.4	.091	.059	.044
60	5.1	.085	.055	.040
70	5.7	.079	.051	.037
80	6.4	.075	.048	.035
90	7.1	.071	.046	.033
100	7.8	.068	.044	.032
110	8.5	.065	.042	.030
120	9.2	.063	.040	.029
130	9.9	.061	.039	.028
140	10.6	.058	.037	.027
150	11.2	.057	.036	.026
160	11.9	.055	.035	.025
170	12.6	.053	.034	.024
180	13.3	.052	.033	.024
190	14.0	.051	.032	.023
200	14.7	.050	.032	.023

Note: Use "A" constant at 5 PSI rP for most applications. On very critical applications, use "A" at 2 PSI rP. You will find in many cases, a 10 PSI rP is not detrimental, and can save money and mounting space.

GT Tabulated values are the solution of where T is for – P2) P2 22.48 68°F and G =1 for Air.

Table 3

Characteristics of the Major Valve Designs

A. Poppet 3-Way and 4-Way	 High flow capacities Minimum lubrication requirements Fast response Self-cleaning poppet seats Pressures of 15 to 150 PSIG (modifications for vacuum to 250 PSIG)
B. Spool Valves (WCS) 3-Way and 4-Way	 Low friction Lower operating pressures Fast response Less wear Long Cycle Life - Under pressure, radial expansion of the seal occurs to maintain sealing contact with the valve bore Non-Lube Service - No lubrication required for continuous valve shifting Bi-Directional Spool Seals - Common spool used for any pressure, including vacuum
C. Packed Bore 4-Way	 Wide range of flow capacities Wide range of flow-path configurations Pilot-operated models available Pressures of vacuum to 150 PSIG
D. Rotary Or Reciprocating Disc 4-Way, manually operated	 Inexpensive Versatility in manual actuation

Cv - Capacity Co-efficients (sometimes called Flow Factors). Each flow path through the valve has its own Cv value. All Cv ratings for each valve cataloged on this page are listed on the front side of this sheet.

$Cv = \frac{Q}{22.48} \sqrt{\frac{GT}{(P_1 - P_2) P_2}}$	 Q = Flow in Standard Cubic Feet per minute (14.7 PSIA at 60°F) P₁= Inlet Absolute Pressure (gauge pressure + 14.7) P₂ = Outlet Absolute Pressure (gauge pressure + 14.7) Note: P₂ must be greater than .53 x P₁ G = Specific Gravity of flowing medium (Air, G =1)
Cv = Q x "A" (Table 2)	T = Absolute Temperature of Air (460 + °F.)

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Technical Data

Graphic Symbols Fluid Power